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Sinopsis

The work treats dynamical systems given by ordinary differential equations in the form \frac{dX^\varepsilon(t)}{dt}=\varepsilon B(X^\varepsilon(t),Y^\varepsilon(t)) where fast motions Y^\varepsilon depend on the slow motion X^\varepsilon (coupled with it) and they are either given by another differential equation \frac{dY^\varepsilon(t)}{dt}=b(X^\varepsilon(t), Y^\varepsilon(t)) or perturbations of an appropriate parametric family of Markov processes with freezed slow variables.

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