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**Título:** Computational Principles Of Mobile Robotics

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**Sinopsis**

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Chapters present algorithms for both visual and nonvisual sensor technologies, including sonar, vision, and laser scanners. In the section on reasoning, the authors thoroughly examine the subject of planning and the issues related to spatial representation. A comprehensive overview of the field, Computational Principles of Mobile Robotics complements its discussion of state-of-the-art methods with 139 illustrations of key current and historical technologies.