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Título: Algorithmic And Computational Robotics. New Directions

Autor: Randall Donald, Bruce (Ed.)

Precio: \$840.00

Editorial:

Año: 2001

Tema:

Edición: 1^a

Sinopsis

ISBN: 9781568811253

Algorithms that control the computational processes relating sensors and actuators are indispensable for robot navigation and the perception of the world in which they move. Therefore, a deep understanding of how algorithms work to achieve this control is essential for the development of efficient and usable robots for a broad field of applications.